

(3,1, ρ)-METRIZABLE TOPOLOGICAL SPACES

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Abstract. In this paper we show that a topological space is pseudo-o-metrizable if and only if it is a (3, 1, ρ)-metrizable. As a corollary we obtain that a topological space is o-metrizable if and only if it is a (3, 1, Δ)-metrizable. At the end it is shown that a topological space is simmetrizable iff it is a (3, 1, Δ)-metrizable, with a metric satisfying $d(x, x, y) = d(x, y, y)$.

1. GENERALIZED METRICS

The geometric problems in metric spaces, and their axiomatic classification have been considered in [Me]. Later, several notion of generalized metrics have been introduced, like the notion of symmetric, o-metric and pseudo-o-metric in [S] and [M], 2-metric in [G1], m-metric in [G2], and generalized metric in [U]. In [D] we have introduced the notion of (n, m, ρ) -metrics. The goal of this paper is to examine the connection between some of those notions and their induced topological structures

First we will define some of these notions.

Let M be a given nonempty set, and let $d : M \times M \mapsto \mathbb{R}_0^+$ be a given map, where \mathbb{R}_0^+ is the set of the nonnegative real numbers. We consider the following axioms;

- (d_1) For each $x \in M$, $d(x, x) = 0$;
- (d_2) For each $x, y \in M$, $d(x, y) = 0$ if and only if $x = y$;
- (d_3) For each $x, y \in M$, $d(x, y) = d(y, x)$;
- (d_4) For each $x, y, z \in M$, $d(x, y) \leq d(y, z) + d(z, x)$.

A map d satisfying (d_1) is called **real distance** in [M], and **pseudo-o-metric** in [N].

A map d satisfying (d_2) is called **o-metric** in [N].

A map d satisfying (d_2) and (d_3) is called **symmetric** in [N].

The axioms (d_2), (d_3) and (d_4) are the axioms for the usual notion of a metric.

The notion of **2-metric** is defined in [G1] as a map $d : M \times M \times M \mapsto \mathbb{R}_0^+$ satisfying:

- (m_1) For each $x, y \in M$, there is $z \in M$, such that $d(x, y, z) \neq 0$;
- (m_2) For each $x, y, z \in M$, $d(x, y, z) = 0$ iff at least two of the three points x, y, z are equal;

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(m_3) For each $x, y, z \in M$, $d(x, y, z) = d(x, z, y) = d(y, z, x)$; and

(m_4) For each $x, y, z, t \in M$, $d(x, y, z) \leq d(x, y, t) + d(x, t, z) + d(t, y, z)$.

The generalization to m -metric is given in [G2].

In [D] we have generalized the notion of equivalence to the notion of an (n, m) -equivalence, and used it to define the notion of (n, m, ρ) -metric. We recall their definitions.

Let n, m be two positive integers, such that $n - m = k > 1$, and let M be a nonempty set.

Let M^n denote the n^{th} Cartesian power of M . We will use the notation $\mathbf{x} = a_1 a_2 \dots a_n$ or just $\mathbf{x} = a_1^n$ instead of $x = (a_1, a_2, \dots, a_n)$ for the elements $\mathbf{x} \in M^n$. For $x \in M$, we denote the element (x, x, \dots, x) by x^n .

Definition 1. The n -fold permutation product of M , i.e. the n^{th} -symmetric power of M , is the set $M^{(n)} = M^n / \sim$, where \sim is the equivalence relation defined on M^n by

$$x_1^n \sim y_1^n \text{ if and only if } (x_1, \dots, x_n) \text{ is a permutation of } (y_1, \dots, y_n). \quad (1)$$

We will use the same notation $\mathbf{x} = a_1^n$ for the elements in $M^{(n)}$ keeping in mind that $a_1^n = b_1^n$ in $M^{(n)}$, for $a_i, b_i \in M$, iff (b_1, b_2, \dots, b_n) is a permutation of (a_1, a_2, \dots, a_n) .

Definition 2. A subset ρ of $M^{(n)}$ is called **symmetric n -relation** on M . A symmetric n -relation on M is called **reflexive n -relation** on M if for each a in M , a^n is in ρ . A symmetric n -relation on M is called **transitive (n, m) -relation** on M , i.e. **(n, m) -transitive**, if for each \mathbf{x} in $M^{(n)}$ and each \mathbf{b} in $M^{(m)}$,

$$(\mathbf{ub} \in \rho \text{ for each } \mathbf{u} \in M^{(k)}, n = m + k, \text{ with } \mathbf{uv} = \mathbf{x}) \text{ implies } \mathbf{x} \in \rho \quad (2)$$

A reflexive n -relation on M which is (n, m) -transitive is called **(n, m) -equivalence** on M . Instead of saying transitive $(n, 1)$ -relation and $(n, 1)$ -equivalence, we say only transitive n -relation on M , and n -equivalence on M .

With these notions, a 2-equivalence is the usual notion of an equivalence relation.

Example 1. (1) The set $\Delta = \{x^n \mid x \text{ in } M\}$ is an (n, m) -equivalence on M for each $1 < m < n$.

(2) The set $\nabla = \{(x, x, y) \mid (x, x, y) \in M^{(3)}\}$ is a $(3, 1)$ -equivalence on M .

(3) The set $\text{Col} = \{(A, B, C) \mid A, B, C \text{ are colinear points in } E^2\}$ is a $(3, t)$ -equivalence on E^2 , for $t = 1, 2$, where E^2 is the euclidean plane.

(4) The set $\text{Com} = \{(A, B, C, D) \mid A, B, C, D \text{ are complanar in } E^3\}$ is a $(4, t)$ -equivalence on E^3 , for $t = 1, 2, 3$, where E^3 is the euclidean 3-dimensional space.

Definition 3. Let ρ be an (n, m) -equivalence on M . A map $d : M^{(n)} \mapsto \mathbb{R}_0^+$, satisfying the following axioms:

(i) $d(\mathbf{x}) = 0$ iff $\mathbf{x} \in \rho$; and

(ii) For each $\mathbf{a} \in M^{(m)}$ and each $\mathbf{x} \in M^{(n)}$, $d(\mathbf{x}) \leq \sum d(\mathbf{ua})$, where the sum is over all the $\mathbf{u} \in M^{(k)}$ such that there is a $\mathbf{v} \in M^{(m)}$ with $\mathbf{uv} = \mathbf{x}$ in $M^{(n)}$;

is said to be an (n,m,ρ)-metric on M, and the pair (M,d) is said to be (n,m,ρ)-metric space.

The sum in (ii) is over all the parts u ∈ M^(k) of x, where n = m + k. In the case m = 1, instead of saying (n,1,ρ)-metric we say only (n,ρ)-metric. When there is no ambiguity about the (n,m)-equivalence ρ, we omit it and write only (n,m)-metric instead of (n,m,ρ)-metric and n-metric instead (n,ρ)-metric.

With the above notions, the notion of a (2,Δ)-metric is the same with the usual notion of metric, while the notion of (3,1,∇)-metric is the notion of 2-metric as defined in [G1].

Example 2. Let Δ be the (n,m)-equivalence defined in Example 1, (1), and let d : M^(n) → ℝ_0^+ be defined by d(x) = 0 iff x ∈ Δ, and d(x) = 1 otherwise. Then it is easy to check that d is an (n,m,Δ)-metric, and so, (M,d) is an (n,m,Δ)-metric space. We call this (n,m,Δ)-metric and (n,m,Δ)-metric space, **discrete (n,m)-metric and discrete (n,m)- metric space.**

Example 3. Let P : (E^2)^(3) → ℝ_0^+ and V : (E^3)^(4)ℝ_0^+ be defined by:

P(A,B,C)=the area of the triangle whose vertices are the points A, B, and C; and

V(A,B,C,D)=the volume of the tetrahedron whose vertices are the points A, B, C, D.

In the case when A,B,C are collinear, P(A,B,C)=0, and when A,B,C,D are coplanar, V(A,B,C,D)=0.

Then, it can be checked that P is a (3,Col)-metric on E^2 and V is a (4,Com)-metric on E^3, i.e. (E^2, P) is a (3,Col)-metric space, and (E^4, V) is a (4,Com)-metric space.

2. TOPOLOGICAL SPACES METRIZABLE BY GENERALIZED METRICS

Next, we will consider only (3,1,ρ)-metrics, and the topologies induced by them. Let (M,d) be a (3,1,ρ)-metrics space. It is possible to define open balls as follows. Let x,y ∈ M, r > 0 and let:

(OB1) B(x,y,r) = {z | d(x,y,z) < r}, the open ball in M with center (x,y) and radius r;

(OB2) B(x,x,r) = {z | d(x,x,z) < r}, the open ball in M with center x and radius r;

(OB3) B(x,r) = {(u,v) | d(x,u,v) < r}, the open ball in M^(2) with center x and radius r.

For all the three definition of open ball, the collection of all open bals is not a base for a topology. Using these collection of open balls as generating sets we define three topologies:

(T1) The topology on M with a base the set of all finite intersections of OB1;

(T2) The topology on M with a base the set of all finite intersections of OB2;

(T3) The topology on M^(2) with a base the set of all finite intersections of OB3.

But following the approach as in [N] and [M], we say that a topological space (M,τ) is:

(3M) **(3, 1, ρ)-metrizable**, if there is a $(3, 1, \rho)$ -metric on M such that U is open iff for each x in U , there is $r > 0$, such that $B(x, x, r) \subseteq U$;

(3WM) **weak (3, 1, ρ)-metrizable**, if there is a $(3, 1, \rho)$ -metric on M such that U is open iff for each x in U , there is $r > 0$, such that $B(x, r) \subseteq U^{(2)}$;

(3SM) **strong (3, 1, ρ)-metrizable**, if there is a $(3, 1, \rho)$ -metric on M such that τ has a base the following collection: $\{U \mid U \subseteq M, \text{ for each } (x, y) \in U^{(2)}, \text{ there is } r > 0, \text{ such that } B(x, y, r) \subseteq U\}$.

The proof of the following proposition is straightforward.

Proposition 1. *Let M be a given $(3, 1, \rho)$ -metric space. The collection of all the sets defined to be open in (3M) together with the empty set is a topology on M . The collection of all the sets defined to be open in (3WM) together with the empty set is a topology on M . The collection $\{U \mid U \subseteq M, \text{ for each } (x, y) \in U^{(2)}, \text{ there is } r > 0, \text{ such that } B(x, y, r) \subseteq U\}$ defined in (3SM) is a base for a topology on M .*

Now we recall the definitions for o -metrizable and pseudo- o -metrizable spaces [N].

A topological space (M, τ) is called:

o -metrizable, if there is a o -metric D on M such that U is open iff for each x in U , there is $r > 0$, such that $T(x, r) = \{y \mid D(x, y) < r\} \subseteq U$;

pseudo- o -metrizable, if there is a pseudo- o -metric D on M such that U is open iff for each x in U , there is $r > 0$, such that $T(x, r) = \{y \mid D(x, y) < r\} \subseteq U$.

Theorem 1. *A topological space (M, τ) is pseudo- o -metrizable iff it is a $(3, 1, \rho)$ -metrizable.*

Proof. Let (M, τ) be pseudo- o -metrizable via a pseudo- o -metric D . Define a map $d: M^{(3)} \mapsto \mathbb{R}_0^+$ by:

$d(x, y, z) = D(x, y) + D(y, x) + D(x, z) + D(z, x) + D(y, z) + D(z, y)$, for $x \neq y \neq z \neq x$, and

$d(x, y, z) = D(a, b)$, for $(x, y, z) = (a, a, b)$ in $M^{(3)}$.

Let ρ be the 3-relation on M defined by:

$$\rho = \{(a, a, b) \in M^{(3)} \mid D(a, b) = 0\}.$$

The definition of ρ and the fact that D is a pseudo- o -metric imply that $\Delta \subseteq \rho$. To show that ρ is a $(3, 1)$ -equivalence, let $(x, y, z) \in M^{(3)}$, let $b \in M$ and let $(x, y, b), (x, b, z), (b, y, z) \in \rho$. The definition of ρ implies that $b = x, b = y, b = z$ or $x = y = z$. W.l.o.g. let $b = x$. Then $(x, y, z) = (x, y, z) \in \rho$. Hence, ρ is a $(3, 1)$ -equivalence on M . The definition of d and the fact that D is a pseudo- o -metric imply that $d(x, y, z) = 0$ iff $x = y = z$, or $(x, y, z) = (a, a, b)$ in $M^{(3)}$ such that $D(a, b) = 0$, i.e. iff $(x, y, z) \in \rho$.

Next, for $x \neq y \neq z \neq x$, and $x \neq a, y \neq a, z \neq a$:

$$\begin{aligned} d(x, y, a) + d(x, a, z) + d(a, y, z) &= \\ &= D(x, y) + D(y, x) + D(x, a) + D(a, x) + D(y, a) + D(a, y) \\ &+ D(x, a) + D(a, x) + D(x, z) + D(z, x) + D(a, z) + D(z, a) \\ &+ D(a, y) + D(y, a) + D(a, z) + D(z, a) + D(y, z) + D(z, y) \end{aligned}$$

$$\geq D(x, y) + D(y, x) + D(x, z) + D(z, x) + D(y, z) + D(z, y) = d(x, y, z).$$

For $x \neq y \neq z \neq x$, and w.l.o.g., $x = a$:

$$d(x, y, a) + d(x, a, z) + d(a, y, z) = D(x, y) + D(x, z) + d(x, y, z) \geq d(x, y, z).$$

For $x = y \neq z$, and $x \neq a$, $z \neq a$:

$$\begin{aligned} & d(x, y, a) + d(x, a, z) + d(a, y, z) \\ &= d(x, y, a) + D(x, a) + D(a, x) + D(x, z) + D(z, x) + D(a, z) + D(z, a) \\ &+ d(a, y, z) \geq D(x, z) = d(x, x, z) = d(x, y, z). \end{aligned}$$

For $x = y \neq z$, and $x = a$:

$$d(x, y, a) + d(x, a, z) + d(a, y, z) = 0 + D(x, z) + d(a, y, z) \geq D(x, z) = d(x, x, z) = d(x, y, z).$$

For $x = y \neq z$, and $z = a$:

$$d(x, y, a) + d(x, a, z) + d(a, y, z) = D(x, a) + D(z, x) + d(a, y, z) \geq D(x, z) = d(x, x, z) = d(x, y, z).$$

For $x = y = z$:

$$d(x, y, a) + d(x, a, z) + d(a, y, z) \geq 0 = D(x, x) = d(x, x, x) = d(x, y, z).$$

Hence, d is a $(3, 1, \rho)$ -metric.

The conclusion follows from the fact that:

$$B(x, x, r) = \{y \mid d(x, x, y) < r\} = \{y \mid D(x, y) < r\} = T(x, r).$$

Conversely, let (M, τ) be $(3, 1, \rho)$ -metrizable space via a $(3, 1, \rho)$ -metric d .

Define $D : M \times M \mapsto \mathbb{R}_0^+$ by $D(x, y) = d(x, x, y)$.

Since d is $(3, 1, \rho)$ -metric and $\Delta \subseteq \rho$, it follows that $D(x, x) = d(x, x, x) = 0$, i.e. D is a pseudo-o-metric on M .

The conclusion follows from the definition of D and the fact that:

$$T(x, r) = \{y \mid D(x, y) < r\} = \{y \mid d(x, x, y) < r\} = B(x, x, r).$$

□

Corrolary 1. A topological space (M, τ) is o-metrizable iff it is a $(3, 1, \Delta)$ -metrizable space.

Proof. Since any o-metric is also a pseudo-o-metric, any o-metrizable space is also $(3, 1, \rho)$ -metrizable space, by Theorem 2, where $\rho = \{(a, a, b) \in M^{(3)} \mid D(a, b) = 0\} = \Delta$. □

Theorem 2. A topological space (M, τ) is symmetrizable iff it is a $(3, 1, \Delta)$ -metrizable, via a $(3, 1, \Delta)$ -metric d , satisfying $d(x, x, y) = d(x, y, y)$ for any $x, y \in M$.

Proof. Let (M, τ) be symmetrizable via a symmetric D . Define a map $d : M^{(3)} \mapsto \mathbb{R}_0^+$ by:

$$d(x, y, z) = D(x, y) + D(x, z) + D(y, z), \text{ for any } x, y, z.$$

Then $d(x, y, z) = 0$ iff $D(x, y) = D(x, z) = D(y, z) = 0$ iff $x = y = z$ iff $(x, y, z) \in \Delta$. Moreover,

$$\begin{aligned} & d(x, y, a) + d(x, a, z) + d(a, y, z) \\ &= D(x, y) + D(x, a) + D(y, a) + D(x, a) + D(x, z) + D(a, z) + D(a, y) + D(a, z) + D(y, z) \end{aligned}$$

$$\begin{aligned} &\geq D(x, y) + D(x, z) + D(y, z) = d(x, y, z); \text{ and} \\ &d(x, x, y) = D(x, x) + D(x, y) + D(x, y) = 2D(x, y) \\ &= D(x, y) + D(x, y) + D(y, y) = d(x, y, y). \end{aligned}$$

Hence, d is a $(3, 1, \Delta)$ -metric d , satisfying $d(x, x, y) = d(x, y, y)$.

The conclusion follows from the fact that:

$$\begin{aligned} B(x, x, 2r) &= \{y \mid d(x, x, y) < 2r\} = \{y \mid D(x, y) + D(y, x) < 2r\} = \\ &= \{y \mid D(x, y) < r\} = T(x, r). \end{aligned}$$

□

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